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“Remaining calm solves great problems.”

Processor

“Processor” and CPU (Central Processing Unit) refers the same—the heart of the computer. It is a chip that is responsible for processing instructions.

17.1 Processors

The computing world came across so many processors. Each of the processors has its own merits and demerits. The following table shows few of the known processors and its characteristics.

Date Introduced	Processor	Coprocessor	Internal Register size (bit)	Data I/O Bus width (bit)	Memory Address Bus width (bit)	Maximum Memory
June, 1978	8086	8087	16	16	20	1MB
June, 1979	8088	8087	16	8	20	1MB
Feb, 1982	286(80286)	80287	16	16	24	16MB
June, 1988	386 SX	80387 SX	32	16	24	16MB
April, 1989	486 DX	Built-in	32	32	32	4MB
March, 1993	Pentium	Built-in	32	64	32	4MB
May, 1997	Pentium II	Built-in	32	64	36	64MB

17.2 Processor Modes

When we look into the history of processors, two processors marked remarkable changes in computing, namely 8088 and 286. These processors are actually responsible for the so called ‘processor modes’.

17.2.1 Real Mode

8088 processor is sometimes referred as 16-bit, because it could execute only 16-bit and could address only 1MB of memory instruction set using 16-bit registers. The processor introduced after 8088, namely 286 was also 16-bit, but it was faster than 8088. So these processors (8088 and 286) can handle only 16-bit software and operating systems like Turbo C++3.0, Windows 3.X, etc.

These processors had some drawbacks:

1. Normally didn't support multitasking
2. Had no protection for memory overwriting. So, there is even a chance to erase the operating system present in memory. In other words, 'memory crash' is unavoidable.

This 16bit instruction mode of 8088 and 286 processors are commonly known as 'Real Mode'.

Note
TC++3.0 is 16-bit. Therefore it is not preferred for commercial applications.

17.2.2 Protected Mode

The first 32-bit processor namely 386, has a built-in mechanism to avoid 'memory crash'. So this 32-bit mode is commonly known as '*protected mode*'. It also supports multitasking. UNIX, OS/2 and Windows NT are the pure 32-bit operating systems. 386 processor are also backward compatible, which means it could even handle 16-bit instructions and could even run on real mode.

17.2.3 Virtual Real Mode

When 386 processor was introduced, programmers were still using 16-bit instructions (real mode) on 386 because 386 executes the 16-bit application much faster. They also resisted 32-bit operating system and 32-bit applications. So when Microsoft tried to introduce Windows 95, a 32-bit operating system, it added a backward compatibility and introduced a mode called 'Virtual real mode'. That is, the programmer may think that it is working under real mode, but it is actually protected from hazardous effects.

17.3 Processor Type

Each processor has its own unique characteristics. When we check for its unique characteristics, we can find whether our processor is 286 or 386 or 586(Pentium). This logic is used to find out the processor type. Processor type is also referred as *CPU Id*.

17.3.1 C program to find processor type

Finding out the processor type using C program is difficult. Any how **Gilles Kohl** came out with a tough C code that can determine processor type (386 or 486).

```
int Test386( void )
{
    char far *p = "\270\001pP\235\234X\313";
```

```

        return!(((int(far*())p)
                )&(( 0x88 + (( 286 | 386 ) *4))<<4));
} /*--Test386( )-----*/

int main( void )
{
    printf( "Running on a %s\n", Test386() ? "386" : "286" );
    return(0);
} /*--main( )-----*/

```

If the code is run on a machine that don't have 386 or 486, you may get a wrong output. For better results we must use Assembly. (We can call it as a limitation of C language!).

17.3.2 Assembly routine to find processor type

The following Assembly routine is by **Alexander Russell**. Using this routine, we can find out our processor type and coprocessor support. This routine can be called from C i.e. you can link the object code with C program.

17.3.2.1 Assembly routines

To understand this Assembly module, read the comments provided in comment line.

```

;-----
; Hardware detection module
;
; Compile with Tasm.
; C callable.
;-----

.model medium, c

        global x_processor          :proc
        global x_coprocessor       :proc

LOCALS
.386

CPUID   MACRO
        db    0fh,          0A2h
ENDM

        .code

i86     equ 0
i186    equ 1
i286    equ 2

```

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```
i386      equ 3
i486      equ 4
i586      equ 5
```

```
;-----
; PC Processor detection routine
;
; C callable as:
;   unsigned int x_processor( );
;
;
x_processor PROC
.8086
    pushf                ; Save flags

    xor  ax,ax           ; Clear AX
    push ax              ; Push it on the stack
    popf                 ; Zero the flags
    pushf                ; Try to zero bits 12-15
    pop  ax              ; Recover flags
    and  ax,0F000h       ; If bits 12-15 are 1 => i86 or i286
    cmp  ax,0F000h
    jnz  @@not_86_186
    jmp  @@is_86_186
```

```
@@not_86_186:

    mov  ax,07000h       ; Try to set bits 12-14
    push ax
    popf
    pushf
    pop  ax
    and  ax,07000h       ; If bits 12-14 are 0 => i286
    jnz  is_not_286
    jmp  is_286
```

```
is_not_286:

    ; its a 386 or higher

    ; check for 386 by attempting to toggle EFLAGS register
    ; Alignment check bit which can't be changed on a 386
.386
    cli
    pushfd
    pushfd
```

```

pop    eax
mov    ebx, eax
xor    eax, 040000h    ; toggle bit 18
push   eax
popfd
pushfd
pop    eax
popfd
sti
and    eax, 040000h    ; clear all but bit 18
and    ebx, 040000h    ; same thing
cmp    eax, ebx
jne    @@moretest
mov    ax, i386
jmp   short @@done

```

; is it a 486 or 586 or higher

@@moretest:

; check for a 486 by trying to toggle the EFLAGS ID bit
; this isn't a foolproof check

```

cli
pushfd
pushfd
pop    eax
mov    ebx, eax
xor    eax, 0200000h    ; toggle bit 21
push   eax
popfd
pushfd
pop    eax
popfd
sti
and    eax, 0200000h    ; clear all but bit 21
and    ebx, 0200000h    ; same thing
cmp    eax, ebx
jne    @@moretest2
mov    ax, i486
jmp   short @@done

```

@@moretest2:

; OK it was probably a 486, but let's double check

```

mov    eax, 1

```

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```
    CPUID
    and  eax, 0f00h
    shr  eax, 8

    mov  ebx, eax
    mov  ax, i586
    cmp  ebx, 5
    je   @@done    ; it was a pentium

    ; it wasn't a 586 so just report the ID

    mov  eax, ebx
    and  eax, 0ffffh

    jmp  short @@done

.8086

is_286:
    mov  ax,i286          ; We have a 286
    jmp  short @@done

@@is_86_186:            ; Determine whether i86 or i186
    push cx              ; save CX
    mov  ax,0FFFFFFh    ; Set all AX bits
    mov  cl,33          ; Will shift once on 80186
    shl  ax,cl          ; or 33 x on 8086
    pop  cx
    jnz  is_186         ; 0 => 8086/8088

is_86:
    mov  ax,i86
    jmp  short @@done

is_186:
    mov  ax,i186

@@done:
    popf

    ret

x_processor endp

.386

.8086
;-----
; PC Numeric coprocessor detection routine
;
```

```

; C callable as:
;   unsigned int x_coprocessor( );
;
; Returns 1 if coprocessor found, zero otherwise

```

```
x_coprocessor PROC
```

```

        LOCAL    control:word

        fninit                    ; try to initialize the copro.
        mov     [control],0        ; clear control word variable
        fnstcw  control           ; put control word in memory
        mov     ax,[control]      ;
        cmp     ah,03h           ; do we have a coprocessor ?
        je     @@HaveCopro       ; jump if yes!
        xor     ax,ax            ; return 0 since nothing found
        jmp    short @@Done

@@HaveCopro:
        mov     ax,1

@@Done:
        ret

x_coprocessor  endp

```

```
end
```

```
;-----
```

17.3.2.2 Calling C program

```
#pragma -mm          /* force to medium memory model */
```

```

int main( void )
{
    int i;
    static char *cpu_str[]=
        {
            "i86",
            "i186",
            "i286",
            "i386",
            "i486",
            "i586",
            "i686"
        };

    i = x_processor( );

```

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```
    if ( i > 6 )
        i = 6;

    printf( "Processor type: %s   CoPro : %s\n", cpu_str[i],
           x_coprocessor( ) ? "Yes" : "No");
    return(0);
} /*--main( )-----*/
```

17.3.3 Another Assembly routine

The success of the above Assembly code by Alexander Russell depends on the code that the compiler produces. So if your compiler doesn't produce the "right" code, you may not get proper results. Here I provide another Assembly code to find out processor type. It is by **Edward J. Berozet**. All these codes use the same logic i.e. checking the unique characteristics of a processor.

This module contains a C callable routine which returns a 16-bit integer (in AX) which indicates the type of CPU on which the program is running. The lower eight bits (AL) contain a number corresponding to the family number (e.g. 0 = 8086, 1 = 80186, 2 = 80286, etc.). The higher eight bits (AH) contain a collection of bit flags which are defined below.

```
; cpuid.asm
;
%           .MODEL    memodel,C                ;Add model support via command
;                                                ;line macros, e.g.
;                                                ;MASM /Dmemodel=LARGE,
;                                                ;TASM /Dmemodel=SMALL, etc.

           .8086
           PUBLIC  cpu_id

;
; using MASM 6.11           M1 /c /F1 CPUID.ASM
;
; using TASM 4.00           TASM CPUID.ASM
;
; using older assemblers, you may have to use the following equate
; and eliminate the .586 directive
;
;CPUID equ "dw 0a20fh"
;
; bit flags for high eight bits of return value
;
HAS_NPU           equ       01h
IS386_287         equ       02h
IS386SX           equ       04h
CYRIX             equ       08h
```



```

NEC          equ      10h
NEXGEN       equ      20h
AMD          equ      40h
UMC         equ      80h

        .code

cpu_id  proc
        push    bx
        push    cx
        push    dx
        push    bp
        mov     bp,sp
        xor     dx,dx                ; result = 0 (UNKNOWN)
;*****
; The Cyrix test
;
;   Cyrix processors do not alter the AF (Aux carry) bit when
;   executing an XOR.  Intel CPUs (and, I think, all the others)
;   clear the AF flag while executing an XOR AL,AL.
;
;*****
TestCyrix:
        mov     al,0fh                ;
        aas                    ; set AF flag
        xor     al,al                ; only Cyrix leaves AF set
        aas                    ;
        jnc     Test8086              ;
        or     dh,CYRIX              ; it's at least an 80386 clone
        jmp     Test486              ;
;*****
; The 80186 or under test
;
;   On <80286 CPUs, the SP register was decremented *before* being
;   pushed onto the stack.  All later CPUs do it correctly.
;
;*****
Test8086:
        push    sp                ; Q: is it an 8086, 80188, or
        pop     ax                ;
        cmp     ax,bp              ;
        je     Test286            ;   N: it's at least a 286
;*****
; The V20/V30 test
;
;   NEC's CPUs set the state of ZF (the Zero flag) correctly after

```

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```
; a MUL. Intel's CPUs do not -- officially the state of ZF is
; "undefined" after a MUL or IMUL.
;
;*****
TestV20:
    xor    al,al                ; clear the zero flag
    mov    al,1                ;
    mul    al                  ;
    jnz    Test186             ;
    or     dh,NEC              ; it's a V20 or a V30
;*****
; The 80186 test
;
; On the 80186, shifts only use the five least significant bits,
; while the 8086 uses all 8, so a request to shift 32 bits will
; be requested as a shift of zero bits on the 80186.
;
;*****
Test186:
    mov    al,01h              ;
    mov    cl,32               ; shift right by 33 bits
    shr   al,cl                ;
    mov    dl,al               ; al = 0 for 86, al = 1 for 186
longTestNpu:
    jmp    TestNpu            ;

;*****
; The 286 test
; Bits 12-15 (the top four) of the flags register are all set to
; 0's on a 286 and can't be set to 1's.
;
;*****
Test286:
    .286
    mov    dl,2                ; it's at least a 286
    pushf                    ; save the flags
    pop    ax                  ; fetch 'em into AX
    or     ah,0f0h            ; try setting those high bits
    push  ax                  ;
    popf                    ; run it through the flags reg
    pushf                    ;
    pop    ax                 ; now check the results
    and   ah,0f0h            ; Q: are bits clear?
    jz    longTestNpu        ; Y: it's a 286

;*****
; The 386 test
```

```

;
;   The AC (Alignment Check) bit was introduced on the 486.  This
;   bit can't be toggled on the 386.
;
;*****
Test386:
    .386
    mov     dl,3                ; it's at least a 386
    pushfd                ; assure enough stack space
    cli
    and     sp, NOT 3        ; align stack to avoid AC fault
    pushfd                ;
    pop     cx              ;
    pop     ax              ;
    mov     bx,ax           ; save a copy
    xor     al,4            ; flip AC bit
    push   ax              ;
    push   cx              ;
    popfd                ;
    pushfd                ;
    pop     cx              ;
    pop     ax              ;
    and     al,4            ;
    sti
    xor     al,bl           ; Q: did AC bit change?
    jnz    Test486         ;   N: it's a 386
    .386P
;*****
; The 386SX test
;
;   On the 386SX, the ET (Extension Type) bit of CR0 is permanently
;   set to 1 and can't be toggled.  On the 386DX this bit can be
;   cleared.
;*****
    mov     eax,cr0
    mov     bl,al           ; save correct value
    and     al,not 10h     ; try clearing ET bit
    mov     cr0,eax       ;
    mov     eax,cr0       ; read back ET bit
    xchg   bl,al          ; patch in the correct value
    mov     cr0,eax       ;
    test   bl,10h         ; Q: was bit cleared?
    jz     TestNpu        ;   Y: it's a DX
    or     dh,IS386SX     ;   N: it's probably an SX
;*****

```

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```
; The 486 test
;
; Try toggling the ID bit in EFLAGS.  If the flag can't be toggled,
; it's a 486.
;
; Note:
; This one isn't completely reliable -- I've heard that the NexGen
; CPU's don't make it through this one even though they have all
; the Pentium instructions.
;*****
Test486:
    .486
    pushfd
    pop     cx
    pop     bx
    mov     dl,4                ;
    mov     ax,bx              ;
    xor     al,20h             ; flip EFLAGS ID bit
    push   ax                  ;
    push   cx                  ;
    popfd                ;
    pushfd                ;
    pop     cx                ;
    pop     ax                ;
    and     al,20h            ; check ID bit
    xor     al,bl              ; Q: did ID bit change?
    jz     TestNpu            ; N: it's a 486

;*****
; The Pentium+ tests
;
; First, we issue a CPUID instruction with EAX=0 to get back the
; manufacturer's name string.  (We only check the first letter.)
;
;*****
PentPlus:
    .586
    push   dx                ;
    xor    eax,eax           ;
    cpuid                ;
    pop    dx                ;
    cmp    bl,'G'           ; Q: GenuineIntel?
    jz     WhatPent         ; Y: what kind?
    or     dh,CYRIX         ; assume Cyrix for now
    cmp    bl,'C'           ;
    jz     WhatPent         ;
    xor    dh,(CYRIX OR AMD) ;
```

```

    cmp     bl,'A'                ;
    jz     WhatPent              ;
    xor     dh,(AMD OR NEXGEN)    ;
    cmp     bl,'N'                ;
    jz     WhatPent              ;
    xor     dh,(NEXGEN OR UMC)    ; assume it's UMC
    cmp     bl,'U'                ;
    jz     WhatPent              ;
    xor     dh,UMC                ; we don't know who made it!
;*****
; The Pentium+ tests (part II)
;
;   This test simply gets the family information via the CPUID
;   instruction
;
;*****
WhatPent:
    push   edx                    ;
    xor    eax,eax                ;
    inc    al                     ;
    cpuid                    ;
    pop    edx                    ;
    and    ah,0fh                ;
    mov    dl,ah                  ; put family code in DL

;*****
; The NPU test
;
;   We reset the NPU (using the non-wait versions of the instruction,of
;   course!), put a non-zero value on the stack, then write the NPU
;   status word to that stack location. Then we check for zero, which
;   is what would be there if there were an NPU.
;
;*****
TestNpu:
    .8087
    .8086
    mov    sp,bp                  ; restore stack
    fninit                    ; init but don't wait
    mov    ax,0EdEdh              ;
    push   ax                     ; put non-zero value on stack
    fnstsw word ptr [bp-2]        ; save NPU status word
    pop    ax                     ;
    or     ax,ax                  ; Q: was status = 0?
    jnz   finish                 ;   N: no NPU
    or     dh,HAS_NPU             ;   Y: has NPU

```

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```
;*****
; The 386/287 combo test
;
; Since the 386 can be paired with either a 387 or 287, we check to
; see if the NPU believes that +infinity equals -infinity. The 387
; says they're equal, while the 287 doesn't.
;
;*****
        cmp     dl,3                ; Q: is CPU a 386?
        jnz     finish             ; N: no need to check
infinities
        fldl                    ; load 1
        fldz                    ; load 0
        fdiv                    ; calculate infinity! (1/0)
        fld     st                ; duplicate it
        fchs                    ; change signs of top inf
        fcompp                   ; identical?
        push   ax                 ;
        fstsw  word ptr [bp-2]    ;
        pop    ax                 ;
        test   ah,40h            ; Q: does NPU say they're
equal?
        jz     finish             ; N: it's a 387
        or     dh,IS386_287      ;
finish:
        mov    ax,dx              ; put our return value in place
        pop   bp                  ; clean up stack
        pop   dx                  ;
        pop   cx                  ;
        pop   bx                  ;

        ret                       ;
cpu_id  endp

        END
;-----
```

Exercises

1. Write a program that can find the current mode of processor (i.e., Real / Protected / Virtual Mode).